nRF7000

Product Specification

v1.1

NORDIC® SEMICONDUCTOR

nRF7000 features

Key features	Applications

• Companion IC with integrated RF for passive and active Wi-Fi® scanning
• Compatible with IEEE 802.11 ax and earlier standards (IEEE 802.11 a/b/g/n/ac)
• Maximum output power 21 dBm
• Dual-band 2.4 GHz and 5 GHz operation
• Single-ended 50 Ω antenna port
• 252 mA @ max output power, 2.4 GHz, 1DSSS
• 260 mA @ max output power, 5 GHz, 6Mbps
• 60 mA RX 2.4 GHz, 56 mA RX 5 GHz
• SPI or QSPI host interface, 3-wire or 4-wire coexistence interface
• Supply voltage range 2.9 – 4.5 V
• Operating temperature range -40° C to 85° C
• 6x6 mm QFN48 package
	• Wi-Fi locationing based on SSID scanning
	  • Asset tracking
	  • Indoor navigation
	  • Biking and sports tracking

Contents

1 Revision history

Date	Version	Description
December 2023	1.1	The following content has been added or updated: • FICR - Defined USERDATA region in FICR • Reference schematic - Updated reference schematic • Electrical specification - Updated electrical specification • Mechanical specification - Corrected dimension L in mechanical specification according to Errata 4 • Editorial changes
June 2023	1.0	First release

2 About this document

This document is organized into chapters that are based on the modules and peripherals available in the IC.

2.1 Document status

The document status reflects the level of maturity of the document.

Document name	Description
Objective Product Specification (OPS)	Applies to document versions up to 1.0. This document contains target specifications for product development.
Product Specification (PS)	Applies to document versions 1.0 and higher. This document contains final product specifications. Nordic Semiconductor ASA reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

Table 1: Defined document names

2.2 Peripheral chapters

Every peripheral has a unique capitalized name or an abbreviation of its name, e.g. TIMER, used for identification and reference. This name is used in chapter headings and references, and it will appear in the Arm Cortex Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer to identify the peripheral.

The peripheral instance name, which is different from the peripheral name, is constructed using the peripheral name followed by a numbered postfix, starting with 0, for example, TIMER0. A postfix is normally only used if a peripheral can be instantiated more than once. The peripheral instance name is also used in the CMSIS to identify the peripheral instance.

The chapters describing peripherals may include the following information:

- A detailed functional description of the peripheral.
- The register configuration for the peripheral.
- The electrical specification tables, containing performance data which apply for the operating conditions described in Recommended operating conditions on page 28.

2.3 Register tables

Individual registers are described using register tables. These tables are built up of two sections. The first three colored rows describe the position and size of the different fields in the register. The following rows describe the fields in more detail.

2.3.1 Fields and values

The **Id (Field Id)** row specifies the bits that belong to the different fields in the register. If a field has enumerated values, then every value will be identified with a unique value id in the **Value Id** column.

A blank space means that the field is reserved and read as undefined, and it also must be written as `0` to secure forward compatibility. If a register is divided into more than one field, a unique field name is specified for each field in the **Field** column. The **Value Id** may be omitted in the single-bit bit fields when values can be substituted with a Boolean type enumerator range, e.g. true/false, disable(d)/enable(d), on/off, and so on.

Values are usually provided as decimal or hexadecimal. Hexadecimal values have a `0x` prefix, decimal values have no prefix.

The **Value** column can be populated in the following ways:

- Individual enumerated values, for example 1, 3, 9.
- Range of values, e.g. [0..4], indicating all values from and including 0 and 4.
- Implicit values. If no values are indicated in the **Value** column, all bit combinations are supported, or alternatively the field's translation and limitations are described in the text instead.

If two or more fields are closely related, the **Value Id**, **Value**, and **Description** may be omitted for all but the first field. Subsequent fields will indicate inheritance with '..'.

A feature marked **Deprecated** should not be used for new designs.

2.3.2 Permissions

Different fields in a register might have different access permissions enforced by hardware.

The access permission for each register field is documented in the **Access** column in the following ways:

Access	Description	Hardware behavior
RO	Read-only	Field can only be read. A write will be ignored.
WO	Write-only	Field can only be written. A read will return an undefined value.
RW	Read-write	Field can be read and written multiple times.
W1	Write-once	Field can only be written once per reset. Any subsequent write will be ignored. A read will return an undefined value.
RW1	Read-write-once	Field can be read multiple times, but only written once per reset. Any subsequent write will be ignored.
W1C	Write 1 to clear	Field can be read multiple times. Bits set to 1 clear (set to zero) the corresponding bit in the register. Bits set to 0 are ignored.
W1S	Write 1 to set	Field can be read multiple times. Bits set to 0 clear (set to zero) the corresponding bit in the register. Bits set to 1 are ignored.

Table 2: Register field permission schemes

3 Product overview

nRF7000 is a wireless companion IC that adds low-power dual band Wi-Fi scanning capabilities to another *System on Chip (SoC)*, *Memory Protection Unit (MPU)*, or *Microcontroller Unit (MCU)* host. It implements the *Physical (PHY)* layer and necessary parts of the *Medium Access Control (MAC)* layer related to scanning.

nRF7000 is compatible with IEEE 802.11ax (also known as Wi-Fi 6) and with earlier standards IEEE 802.11 a/b/g/n/ac.

nRF7000 has been designed for *Internet of Things (IoT)* applications, and is ideal for adding Wi-Fi *Basic Service Set Identifier (BSSID)* scanning capabilities to existing locationing solutions.

Nordic Semiconductor provides reference host support implementations for nRF91 Series, nRF52840, and nRF5340 devices, but nRF7000 may also be used with other hosts with sufficient processing and memory capacity. It connects to the host SoC or MCU through a *Serial Peripheral Interface (SPI)* or *Quad Serial Peripheral Interface (QSPI)* serial interface (which can optionally be encrypted) and supports coexistence with other radio protocols through a dedicated 3-wire or 4-wire coexistence interface.

nRF7000 supports dual-band 2.4 GHz and 5 GHz band operation. The antenna ports are single-ended 50 Ω.

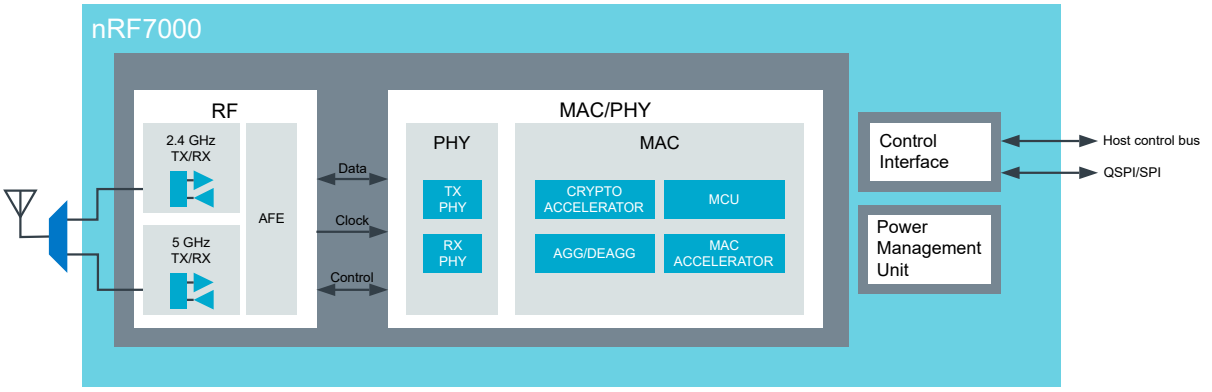


Figure 1: nRF7000 block diagram

4 Host connection

nRF7000 is a wireless companion device that is connected to a host *MCU* or application processor. It is connected to the host through a *QSPI* (6-wire) or *SPI* (4-wire) for data and a 3-wire or 4-wire coexistence control interface for hosts that include a *Bluetooth*® LE/IEEE 802.15.4 radio. In addition, two lines (HOST_IRQ and BUCKEN) are required. The user application executes on the host MCU.

The following figure shows a system with nRF7000 and a host MCU.

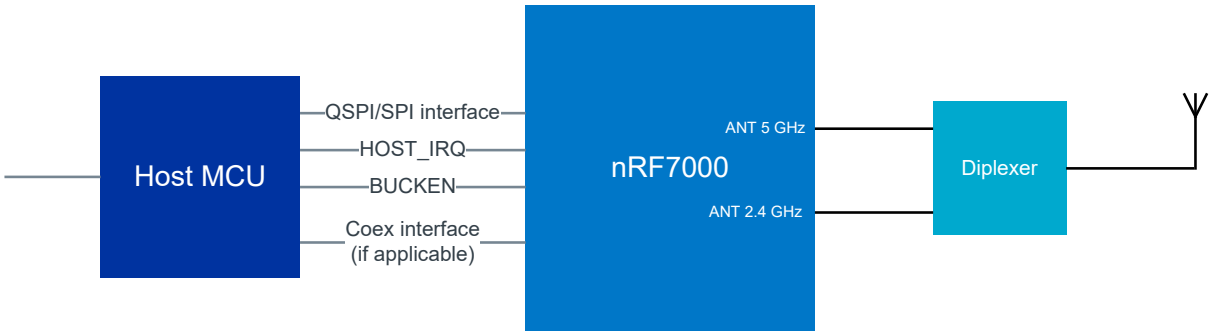


Figure 2: Functional block diagram with generic host MCU

The following figure shows nRF7000 together with nRF9160 to achieve a combined LTE and Wi-Fi scanning solution. nRF9160 functions as a host and common interface to the wireless system.

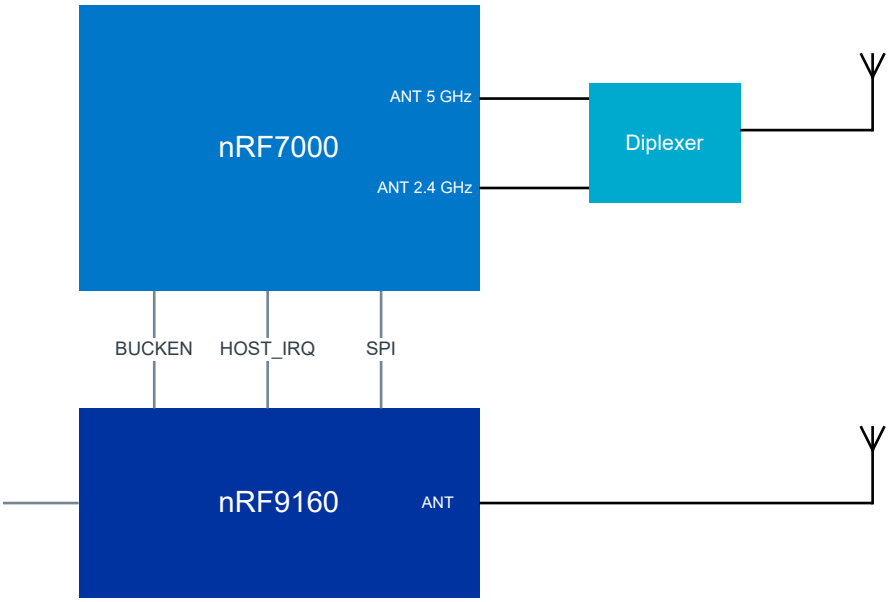


Figure 3: Functional block diagram with nRF host

5 Power and clock management

The power and clock management system in nRF7000 is optimized for ultra-low power applications to ensure maximum power efficiency.

5.1 Power states

nRF7000 has three power states: Shutdown, Sleep, and Active.

Shutdown

A fully inactive state where no state information is retained except for the contents of the *One Time Programmable (OTP) memory*. nRF7000 will only respond to a BUCKEN assertion (input to *Power Management Unit (PMU)*).

The following conditions occur during Shutdown state:

- PMU: Off
- Analog circuits: All circuits off
- Baseband logic and scratch RAMs: Off
- Retention RAMs: Off
- *SPI/QSPI*: Off

Sleep

A low-power state where state information is retained and transitioning to Active state can occur rapidly. The device will be in the Sleep state between scan requests. In this state, the device is clocked through the internal 32 kHz *RC oscillator* (*Real-time Clock (RTC)*), and will be awakened through the host interface making a scan request.

The following conditions occur during Sleep state:

- PMU: Low-power mode (*Pulse-Frequency Modulation (PFM)*)
- Analog circuits: RTC active, register state retained. All other circuits are powered down.
- Baseband logic and scratch RAMs: Off
- Retention RAMs: Retained
- SPI/QSPI: On

Active

In the Active state, the device will be in one of the Active sub-states: Transmit, Receive, or Idle. The high frequency crystal oscillator derived clocks are active and the appropriate RF section components are enabled as required. The Idle sub-state is a short term transitory state used when Receive is not required, but Sleep cannot be exploited (for example, upon early termination of an RX packet).

The following conditions occur during Active state:

- PMU: High-power mode (*Pulse-Width Modulation (PWM)*)
- Analog circuits: All circuits powered (including crystal oscillator). The circuits are enabled according to Active sub-state (TX, RX, or IDLE)
- Baseband logic and scratch RAMs: On
- Retention RAMs: Active
- SPI/QSPI: On

5.2 Power state operation

Apart from transitions in or out of Shutdown state through the BUCKEN pin, all transitions between Sleep and Active states are automatic and do not rely on any control pin assertion or de-assertion.

Shutdown state is achieved by de-assertion on the BUCKEN pin. Asserting BUCKEN will result in the Active (IDLE sub-state) state being entered. The host will initiate the boot sequence through *SPI*/*QSPI*, culminating in the Sleep state being entered. This is the lowest power non-Shutdown state that can be achieved. Transitions from Active to Sleep are fully controlled by nRF7000. Transitions from Sleep to Active are determined by both the host and nRF7000. Sleep is entered opportunistically whenever there is no scan activity associated with a scan request from the host.

Transitioning from Shutdown or Sleep state to Active state involves the following steps:

1. Switch the *Power Management Unit (PMU)* to high power mode (*PWM*).
2. Apply power to the digital logic, RAMs, and analog circuits.
3. Start the 40 MHz crystal oscillator and allow to settle.
4. Start the baseband PLL and allow to settle.
5. Boot all processor cores.
6. Execute baseband initializations.
7. Execute RF initializations and calibrations.

The initial steps consume equal duration whether originating in Shutdown or Sleep, while the baseband and RF initializations are dependent on the originating state. In particular:

- Full baseband initializations are required from Shutdown (including transferring the *Factory Information Configuration Registers (FICR)* information from *OTP memory* into retention RAM), while in Sleep some of the state is retained in retention RAMs.
- Complete RF calibrations are required from Shutdown, including across channels to support scanning. From Sleep, only minimal initialization or calibration on the operating channel is required.

See Electrical specification on page 30 for timing information.

5.3 Clock accuracy considerations

The crystal oscillator is active during normal operation, and is the clock reference for the RF synthesizer, the *Analog-to-Digital Converter (ADC)*/*Digital-to-Analog Converter (DAC)* sample clocks, and the baseband logic. The *RTC* is active during sleep state, and is used to run the wakeup timer used as part of Wi-Fi Power Save. The crystal oscillator is inactive during sleep.

The *IEEE 802.11 specification* defines the accuracy of the Wi-Fi carrier frequency to be within ± 20 ppm (in 5 GHz), which in turn defines the required accuracy of the external crystal. There is provision to trim the crystal oscillator through a value programmed into the *OTP memory* on the nRF7000 device (or any other available non-volatile memory). This trimming will compensate for the combined frequency offset resulting from the crystal itself as well as any crystal oscillator variation at room temperature. The crystal and crystal oscillator will both exhibit frequency drift across temperature, and the crystal will also be subject to aging. The combination of these temperature and aging effects, along with the trimming accuracy, will consume the majority of the ± 20 ppm allowance, assuming a crystal with ± 10 ppm stability over temperature. The crystal tolerance (that is, accuracy at room temperature) is less important since this will be trimmed out by the crystal oscillator trim function (up to ± 20 ppm). The crystal oscillator/crystal is typically trimmed by transmitting Wi-Fi packets through the antenna connector and using a *Vector Signal Analyzer (VSA)* to measure the frequency offset. Alternatively, a generic spectrum analyser can be used to measure the frequency offset on a transmitted *Carrier Wave (CW)*.

6 Software stack

This section details the partitioning of the networking stack and the IEEE 802.11 Wi-Fi stack across the host *MCU* and nRF7000.

This description is based on the Zephyr™ networking stack and an nRF9160 host MCU. However, the partitioning applies equally to other operating systems and host MCUs supporting a compatible *SPI*/*QSPI*.

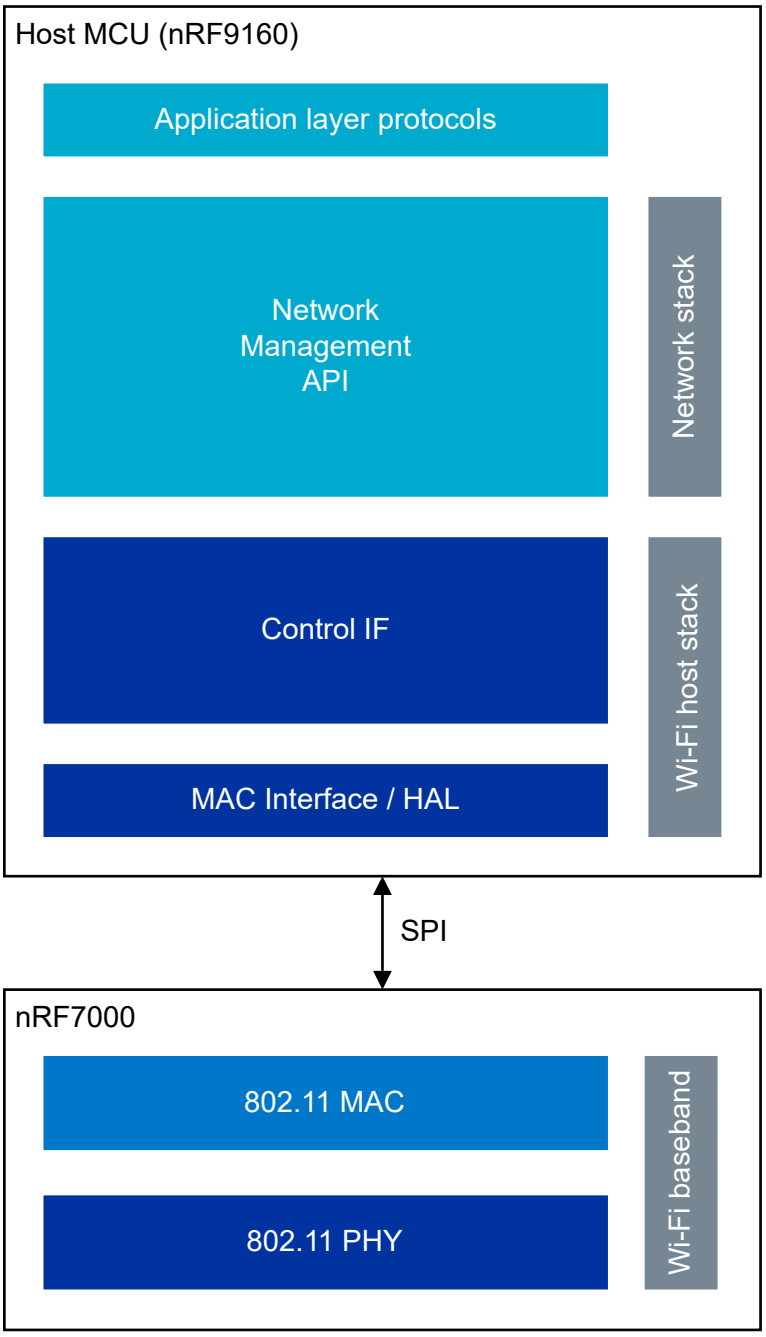


Figure 4: Network stack architecture

The Wi-Fi driver executes on the host MCU (for example, nRF9160) and communicates with the MAC layer on nRF7000 through SPI.

6.1 Firmware updates

nRF7000 supports device firmware updates for bug fixes, security fixes, or additional functionality.

The updates are performed by patching the firmware. The firmware patches are downloaded from the host to the device for patching the ROM-based firmware. The patch download is fully automatic and handled by the Wi-Fi driver software running on the host device.

Patches are downloaded to the nRF7000 device when powering up the device. Patches are downloaded into the patch memory, which is retained during sleep. The maximum patch size is 128 KB.

Patches are linked to a Wi-Fi driver version and delivered as a byte array included in the Wi-Fi driver.

7 Quad Serial Peripheral Interface

The *SPI*/*QSPI* slave interface is compatible with the nRF52, nRF53, and nRF91 Series SPI/QSPI master interface.

The main features of the QSPI slave interface are:

- Single/quad SPI input/output
- Supports up to 32 MHz clock frequency
- Single and block mode read/write accesses
- On-the-fly encryption and decryption

7.1 QSPI commands

nRF7000 supports several *QSPI* commands.

Command (byte)	RDSR (read status register 0)	RDSR1 (read status register 1)	RDSR2 (read status register 2)	WRSR2 (write status register 2)	CIPHER INIT (Initialize cipher)	FAST READ (fast read data)	READ4 (4 x I/O read command)	PP (Page program)	PP4 (Quad page program)
1st byte	0x05	0x1F	0x2F	0x3F	0x4F	0x0B	0xEB	0x02	0x38
2nd byte					NONCE1	AD1	ADD (4) and Dummy (4)	AD1	ADD (4)
3rd byte					NONCE2	AD2	Dummy (4)	AD2	
4th byte					NONCE3	AD3		AD3	
5th byte					NONCE4	Dummy			
Action	To read out the values of status register 0	To read out the values of status register 1	To read out the values of status register 2	To write in the values of status register 2	To enable the steam cipher and initialize the NONCE register	n bytes read out until SS goes high	n bytes read out by 4 x I/O until SS goes high	to program the selected page	Quad input to program the selected page

Table 3: QSPI commands

For RDSR, RDSR1, RDSR2, FAST_READ, and READ4, the shifted-in instruction sequence is followed by a data-out sequence. After any bit of data being shifted out, the SS can be high.

For CIPHER_INIT, PP, and PP4, the SS must go high exactly at the 4th byte (32 bits) boundary or the value will not be stored.

For WRSR2, the SS must go high exactly at the 1st byte (8 bits) boundary or the value will not be stored.

The following figure shows the timing diagram for the RDSR command. The other commands that access status registers have the same format but with a different 1st byte.

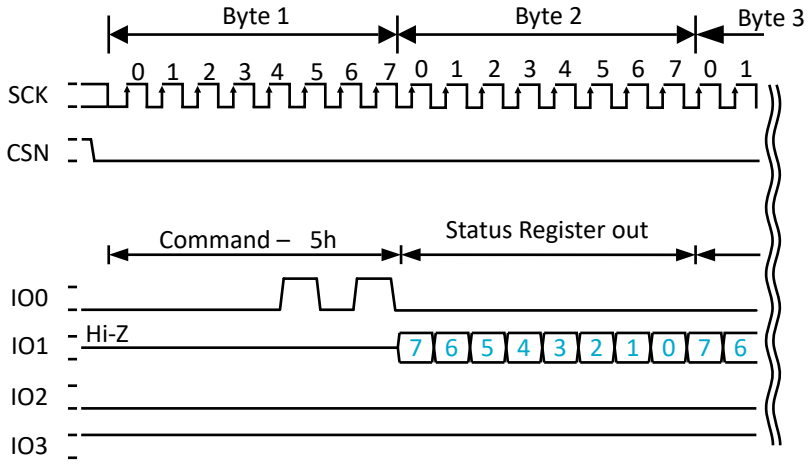


Figure 5: RDSR (Read status register 0)

The following figure shows the timing diagram for the cipher initialization command.

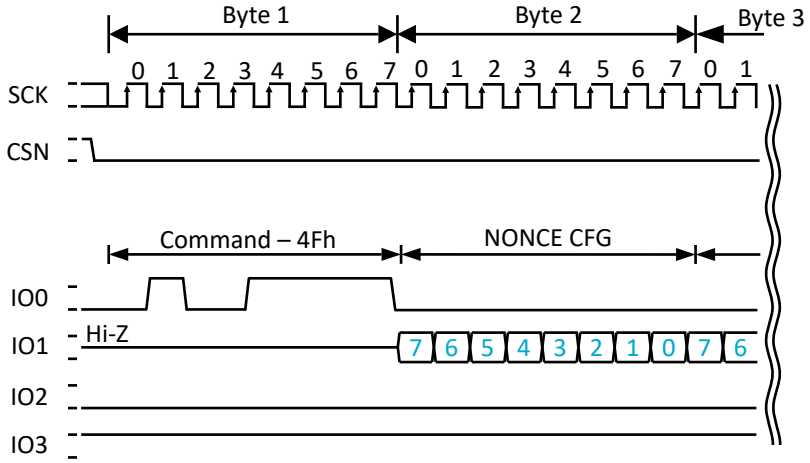


Figure 6: CIPHER INIT (Initialize cipher)

The following figures show the timing diagram for the data read and program commands.

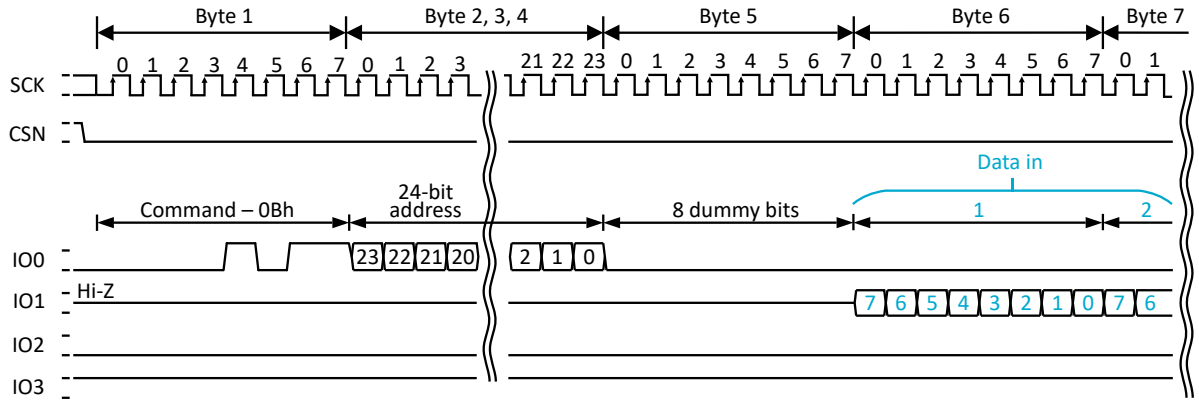


Figure 7: FASTREAD (Read bytes at higher speed)

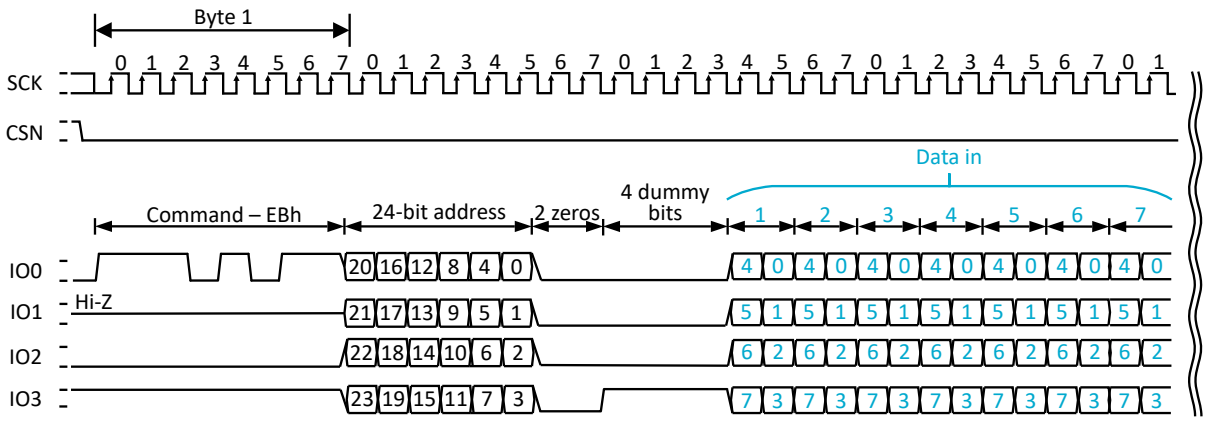


Figure 8: READ4IO (Quad-read input/output)

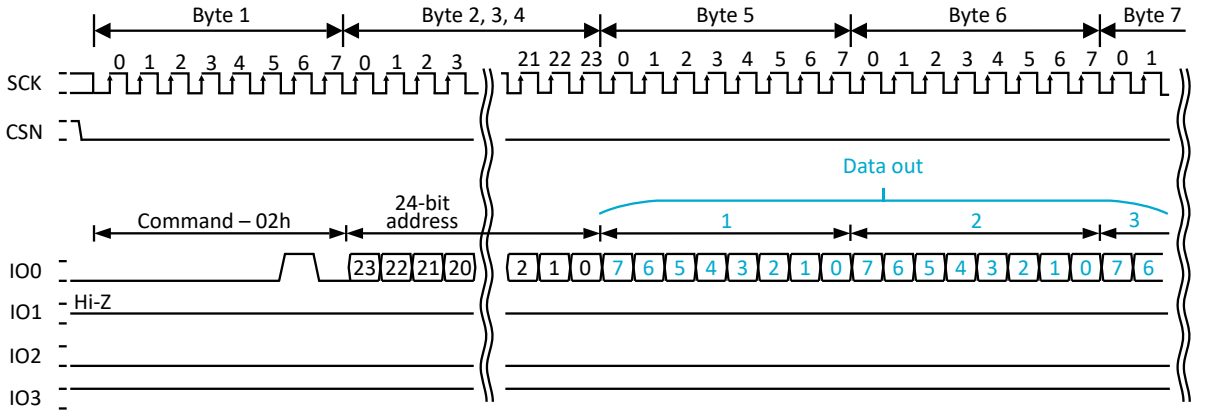


Figure 9: PP (Page program)

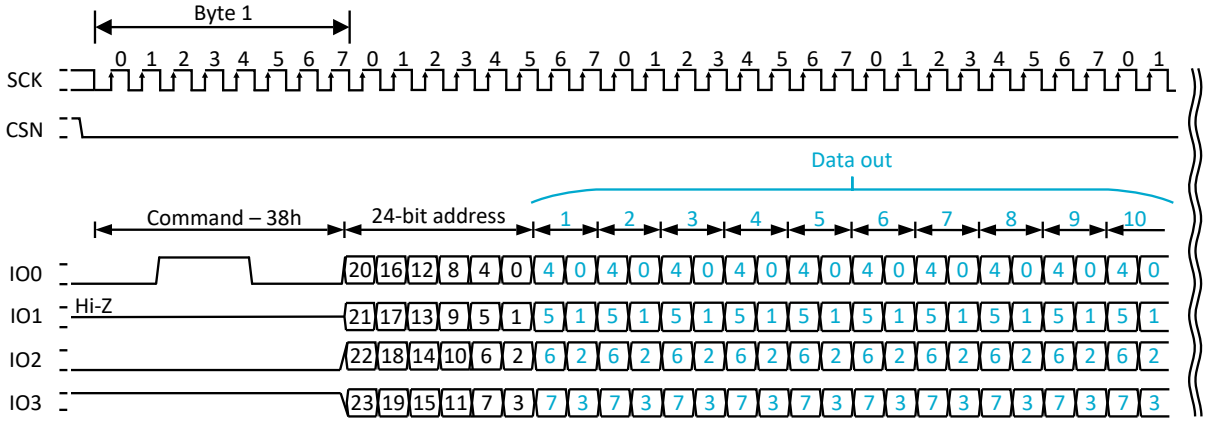


Figure 10: PP4IO (Quad-page program input/output)

7.2 Stream cipher

The data transactions between the master and the slave can be protected using stream cipher encryption. Encryption can be configured and enabled with the CIPHER_INIT command. The encryption key (ENC.KEY[127:0]) is stored in QSPI.KEY.

The following figure shows the stream cipher block with the configuration inputs. The stream cipher uses an AES 128 encryption operation to form the keystream from key, nonce, and external memory address. The keystream then combines each 32-bit plaintext digit one at a time with the corresponding digit of the keystream.

The same nonce and key must be used for both encryption and decryption of the same memory address. Stream ciphers are symmetric. They do not differentiate between encrypting or decrypting, reading or writing.

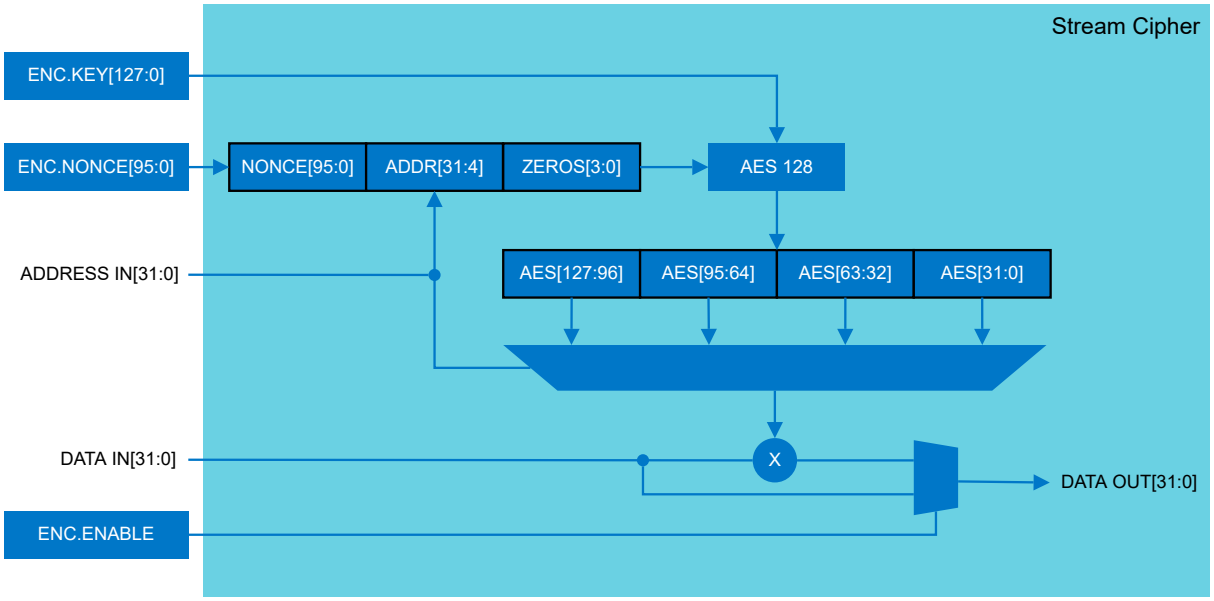


Figure 11: Stream cipher

Stream cipher	Value
ENC.KEY [127:0]	{CIPHER_KEY3[31:0], CIPHER_KEY2[31:0], CIPHER_KEY1[31:0], CIPHER_KEY0[31:0]}
ENC.NONCE [95:0]	{NONCE_CNT[31:0], NONCE_CFG[31:0], CIPHER_NONCE0[31:0]}
ADRESS IN [31:0]	{8'h00, SPI Address [23:0]}
ENC.ENABLE	CIPHER ENABLE

Notes:

- CIPHER_KEY3, CIPHER_KEY2, CIPHER_KEY1, CIPHER_KEY0, CIPHER_NONCE0 : IP parameters (32 bit).
- NONCE_CFG : The NONCE Configuration register. Initialized with the CIPHER_INIT command.
- NONCE_CNT: The NONCE Counter register. Initialized to d0 with the CIPHER_INIT command. A pre-increment is done to the NONCE_CNT register at the start of the QSPI transaction (FAST_READ, READ4, PP, PP4).
  - Single read/write mode : increment always.
  - Multiple read/write mode : increment only if the received SPI address differs from the next expected SPI address (last SPI address +1) or if the last transaction was not in multiple mode.
- CIPHER ENABLE : The Cipher Enable register is 1'b0 by default and it is set to 1'b1 with the CIPHER_INIT command.

Table 4: Stream cipher configuration

8 Coexistence

nRF70 Series devices have a highly configurable coexistence hardware to help mitigate interference between WLAN and Bluetooth LE/IEEE 802.15.4 devices (Thread®, Zigbee®).

A *Packet Traffic Arbitration (PTA)* module, connected to the CH logic function, facilitates the mitigation of various interference scenarios through a highly-programmable fabric. The coexistence hardware enables flexible output signals that support interface configurations like 3-wire and 4-wire. The primary schemes supported are:

- Shared Antenna mode – The PTA makes priority decisions, controls the switch between Bluetooth LE/IEEE 802.15.4 and Wi-Fi. The PTA also grants TX/RX requests from the Bluetooth LE/IEEE 802.15.4 device. Only one interface, either Bluetooth LE/IEEE 802.15.4 or or Wi-Fi is connected to the antenna at any time.
- Separate Antenna mode – The PTA makes priority decisions, granting TX/RX requests from Bluetooth LE/IEEE 802.15.4. Each interface is permanently connected to its own antenna.

The following figure shows the architecture of the coexistence hardware with details about the PTA control lines.

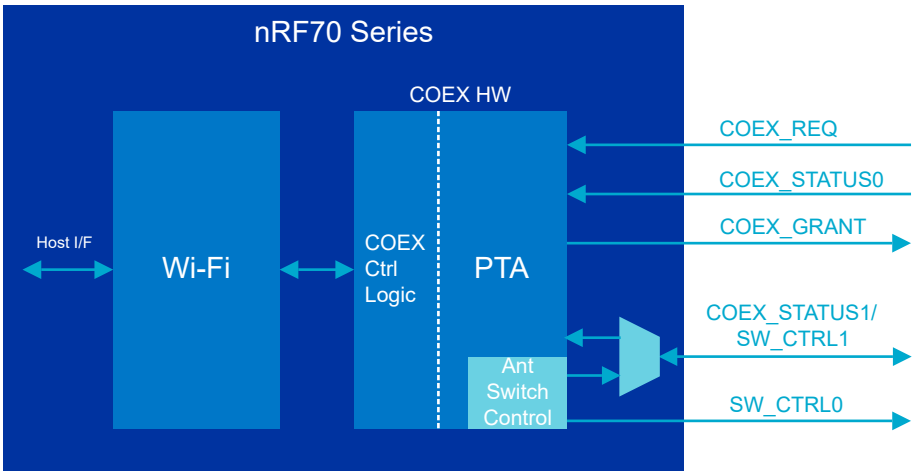


Figure 12: Coexistence hardware architecture

Signal name	I/O	Requirement	Bluetooth LE/ IEEE 802.15.4 signal (3-wire/4-wire)	Description	Scan-only function
COEX_REQ	Input	Mandatory for 3-wire and 4-wire	SR_REQUEST	Bluetooth LE/IEEE 802.15.4 device requesting a TX/ RX transaction	Does not influence COEX_GRANT.
COEX_STATUS0	Input	Mandatory for 3-wire and 4-wire	SR_STATUS	Indicates if the Bluetooth LE/ IEEE 802.15.4 transaction is TX or RX. If the device supports a Priority signal, Priority is muxed with TX/RX on this signal based on the timing diagrams.	Does not influence COEX_GRANT.
COEX_GRANT	Output	Mandatory for 3-wire and 4-wire	SR_GRANT	Indicates that the Bluetooth LE/IEEE 802.15.4 device is granted access for this transaction.	Only de-asserted during a Wi-Fi scan operation in the 2.4 GHz band.
COEX_STATUS1/ SW_CTRL1	Input/ Output	Optional for 3-wire	SR_PTI/ RF_SW_CTRL1	In 4-wire mode, this carries the Bluetooth LE/ IEEE 802.15.4 1 bit priority signal. In 3-wire Shared Antenna mode, this can be optionally used as a second antenna switch control signal.	Does not influence COEX_GRANT in 4-wire mode. Can function as a second switch control signal in 3-wire mode.
SW_CTRL0	Output	Mandatory for 3-wire and 4-wire Shared Antenna mode. Optional otherwise	RF_SW_CTRL0	Used for antenna switch control in Shared Antenna mode.	Functions as a switch control in Shared Antenna mode.

Table 5: Coexistence hardware signals

Note: The behavior of SW_CTRL0/1 is programmable and dependent on the configured coexistence mode and switch control interface.

8.1 Bluetooth LE/IEEE 802.15.4 timing

This section provides Bluetooth LE/IEEE 802.15.4 timing diagrams and parameters.

3-wire with multiplexed priority

The following diagram shows external Bluetooth LE/IEEE 802.15.4 timing parameters when SR_STATUS carries both priority and TX/RX information in a time multiplexed manner.

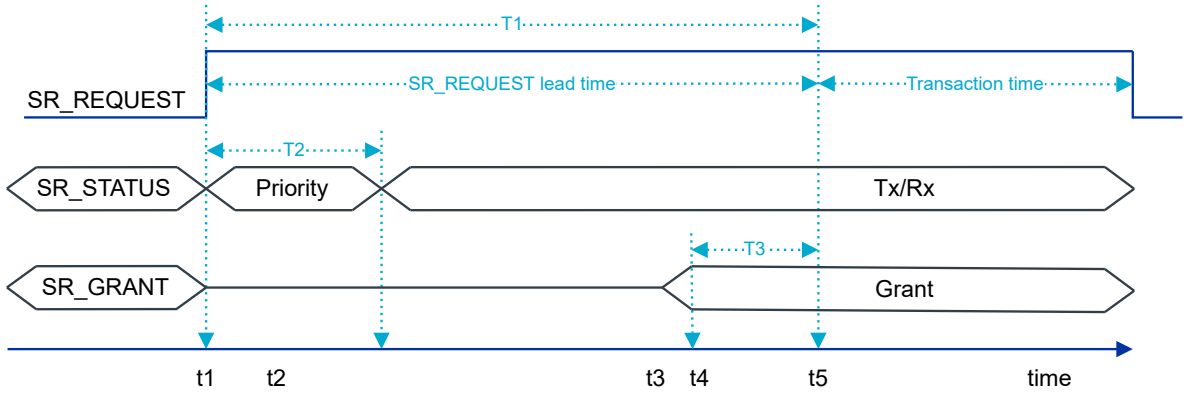


Figure 13: 3-wire timing with priority multiplexing

Parameter	Description
T1: SR_REQUEST lead time period	The time SR_REQUEST is asserted before actual transactions.
T2: SR_STATUS	The time when SR_STATUS is sampled to get SR_PTI information.
T3: SR_GRANT	The time before PTA should post SR_GRANT so that it is stable to be considered by the Bluetooth LE/IEEE 802.15.4 device.

Table 6: Bluetooth LE/IEEE 802.15.4 timing parameters

The Bluetooth LE/IEEE 802.15.4 timing parameters are used to derive *PTA* timing parameters. The following table describes the relationship between PTA timing parameters and Bluetooth LE/IEEE 802.15.4 timing parameters.

PTA timing parameter	Relation with Bluetooth LE/IEEE 802.15.4 timing parameter
Bluetooth LE/IEEE 802.15.4 device status priority sampling time (t2)	t1 < t2 < (t1+T2)
PTA arbitration decision time (t3)	(t1+T2) < t3 < (T1-T3)

Table 7: PTA and Bluetooth LE/IEEE 802.15.4 timing parameters

Time instance	Description
t1	The time instance when SR_REQUEST is asserted.
t2	The time instance when SR_STATUS is sampled to get SR_PTI information. This can be any time during T2.
t3	The time instance when PTA takes an arbitration decision and posts SR_GRANT to the Bluetooth LE/IEEE 802.15.4 device. This is chosen a couple of microseconds before the start of the *SR grant lead time period*. This ensures that SR_GRANT is asserted as close to *SR grant lead time period* and is stable by the time the Bluetooth LE/IEEE 802.15.4 device uses this information to continue or abort the transaction.
t4	The time instance when the *SR grant lead time period* starts. This is the time when SR_GRANT must be stable to be considered by the Bluetooth LE/IEEE 802.15.4 device.
t5	The time instance when the actual transaction of the Bluetooth LE/IEEE 802.15.4 device starts. This is the time when the signaling period ends and the transaction period starts. Bluetooth LE/IEEE 802.15.4 Tx and Rx information is provided by changing the SR_STATUS signal level appropriately. PTA should track SR_STATUS if SR_REQUEST is high and update the information SR_TX_RX.

Table 8: Time instances

3-wire without multiplexed priority

If SR_STATUS carries only one parameter information (3-wire, no priority mode), then the default information that it carries is SR_TX_RX. In this case, SR_STATUS is set to TX or RX when SR_REQUEST is HIGH. The following diagram shows SR_STATUS only carrying TX/RX information. The signals are represented as a bus even though they are single bit ports to indicate transitions happening on the ports.

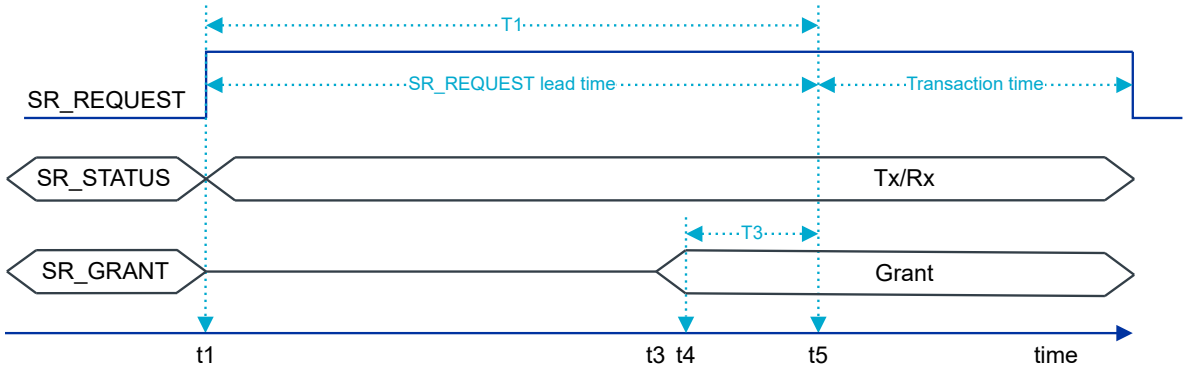


Figure 14: 3-wire timing without priority multiplexing

During the transaction, the Bluetooth LE/IEEE 802.15.4 device changes SR_STATUS appropriately to indicate TX and RX information. PTA continuously tracks SR_STATUS while SR_REQUEST is high and updates SR_TX_RX status internally for corresponding COEX behavior.

4-wire timing

In the following diagram, Bluetooth LE/IEEE 802.15.4 priority is explicitly signaled on the BT_COEX_STATUS1 pin.

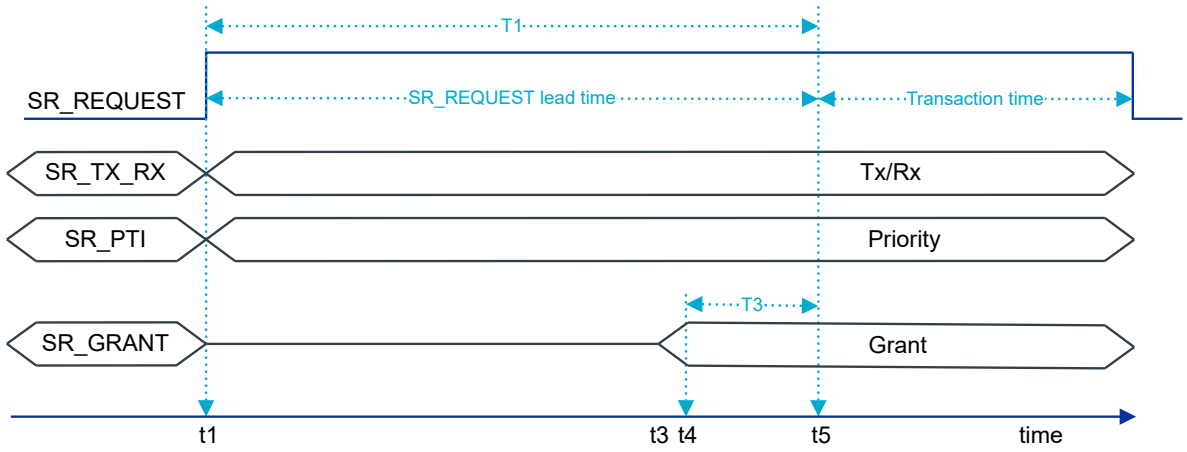


Figure 15: 4-wire timing

9 OTP memory programming

nRF7000 includes a 128 x 32-bit *OTP memory*. This memory is partitioned into two regions, a factory programmed region and a customer programmed region, each containing 64 x 32-bit locations.

The factory programmed region contains information related to production and trim values. The customer programmed region contains:

- Encryption key used to protect the QSPI traffic (4 words)
- MAC addresses for VIF0 and VIF1 (4 words)
- Module level calibration coefficient (1 word)
- OTP memory protection control (4 words)
- Default register control (1 word)
- Reserved (24 words)
- User data region (26 words)

QSPI encryption is optional. This is enabled at runtime through a QSPI command. If this feature is not required, the OTP memory locations can remain unprogrammed. For security reasons, the encryption key cannot be read once programmed.

The MAC address fields in the OTP memory are accessed by firmware when powering up the device and presented to the host through an SPI/QSPI-based event as part of the boot phase. The host driver is responsible for configuring the MAC addresses as part of device configuration. As such, the MAC addresses stored in OTP memory can be overwritten by the host. Using this mechanism, the MAC addresses in the OTP memory can remain unprogrammed if an alternate host side storage is used. For the scan-only functionality supported by nRF7000, only the VIF0 MAC address is required.

The only module level calibration coefficient is the crystal oscillator trim. This is required to minimize the frequency offset resulting from the external 40 MHz crystal. See Device Commissioning and Characterization for information related to calibration.

Although the OTP memory is *one time programmable*, any bit still in a `1` state can be reprogrammed into a `0` state. To avoid deliberate or inadvertent modification of the OTP memory data, a protection mechanism is provided. The protection registers initially need to be programmed to 0x50FA50FA in order to activate programming of the remaining locations. Once OTP memory programming is complete, the protection registers should be programmed to 0x00000000, at which point the OTP memory can never be modified.

In addition to the logical protection mechanism described above, a programming voltage needs to be applied to the OTPVDD pin in order to enable programming. The programming voltage is 2.5 V, while for reads it is 1.8 V. To coordinate the OTPVDD supply voltage with read and write operations, it is recommended to drive this supply from the POWERIOVDD output pin on nRF7000. This also ensures there will be no leakage associated with the OTP memory across sleep cycles, where the digital supply rail is removed.

The OTP memory is indirectly mapped, and as such read and writes are achieved using address, data, and mode registers. The OTP memory programming utility implements this programming, along with appropriate control of the OTPVDD supply through the POWERIOVDD output.

10 FICR - Factory Information Configuration Registers

The Factory Information Configuration Registers (FICR) are stored in the *OTP memory*.

FICR has two regions:

- A factory-programmed region that contains device information and has the INFO group registers.
- A customer-programmable region that contains empty registers for the customer to write data to. It has the QSPI, MAC, and CALIB group registers.

Access to the customer-programmable region is controlled using the PROTECTION register.

The PROTECTION scenarios are:

- When PROTECTION is unprogrammed, neither read not write is enabled.
- When PROTECTION is programmed to 0x50FA50FA, full read and write access is enabled.
- When PROTECTION is programmed to 0x00000000, access protection is applied and readout of QSPI.KEY is prevented.

The following table shows the access protection for the different register groups.

Register group	0xFFFFFFFF	0x50FA50FA	0x00000000
QSPI.KEY	-	R/W	-
MAC.ADDRESS	-	R/W	R
CALIB	-	R/W	R

Table 9: PROTECTION register settings for access control to customer programmable region

10.1 Registers

Register overview

Register	Offset	Description
INFO.PART	0x0C0	Part code
INFO.VARIANT	0x0C4	Part variant
INFO.UUID[n]	0x0D0	Universal Unique ID
REGION.PROTECT[n]	0x100	Region protection
QSPI.KEY[n]	0x110	QSPI link symmetric encryption key (ENC.KEY)
MAC[n].ADDRESS0	0x120	MAC address for VIFn
MAC[n].ADDRESS1	0x124	MAC address for VIFn
CALIB.XO	0x130	XO adjustment
REGION_DEFAULTS	0x154	Customer region register usage indicator
USERDATA[n]	0x198	User data region

10.1.1 INFO.PART

Address offset: 0x0C0

Part code

Bit number				31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID				A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A
Reset 0xFFFFFFFF				**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**
ID	R/W	Field	Value ID	Value																															
A	R	PART																																	
			N7000	0x7000																															
				nRF7000																															

10.1.2 INFO.VARIANT

Address offset: 0x0C4

Part variant

Bit number				31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID				A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A
Reset 0xFFFFFFFF				**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**
ID	R/W	Field	Value ID	Value																															
A	R	VARIANT																																	
				ASCII																															
			A00	0x413030																															
				A00																															

10.1.3 INFO.UUID[n] (n=0..3)

Address offset: 0x0D0 + (n × 0x4)

Universal Unique ID

Bit number				31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID				A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A
Reset 0xFFFFFFFF				**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**
ID	R/W	Field	Value ID	Value																															
A	R	UUID																																	
				Universal Unique ID																															

10.1.4 REGION.PROTECT[n] (n=0..3)

Address offset: 0x100 + (n × 0x4)

Region protection

Used to set access restrictions for FICR. Refer to description in top of chapter. All 4 registers need to be set to the same value to change protection state.

Bit number				31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A A A A A A A A A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFFF				**1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1**
ID	R/W	Field	Value ID	Value	Description
A	RW	VALUE			Protection value
			Undefined	0xFFFFFFFF	Undefined
			Open	0x50FA50FA	Open
			Restricted	0x00000000	Restricted

10.1.5 QSPI.KEY[n] (n=0..3)

Address offset: 0x110 + (n × 0x4)

QSPI link symmetric encryption key (ENC.KEY)

KEY[0] represent key bits 31:0, KEY[1] is bits 63:32, KEY[2] is bits 95:64, KEY[3] is bits 127:96

Bit number				31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A A A A A A A A A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFFF				**1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1**
ID	R/W	Field	Value ID	Value	Description
A	RW	KEY			QSPI link symmetric encryption key

10.1.6 MAC[n].ADDRESS0 (n=0..1)

Address offset: 0x120 + (n × 0x8)

MAC address for VIFn

Most significant 4 bytes of MAC address b6:b5:b4:b3:b2:b1

Bit number				31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D D D D D D D D C C C C C C C C B B B B B B B B A A A A A A A A
Reset 0xFFFFFFFF				**1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1**
ID	R/W	Field	Value ID	Value	Description
A	R	b6			6th byte (b6) of MAC address
B	R	b5			5th byte (b5) of MAC address
C	R	b4			4th byte (b4) of MAC address
D	R	b3			3rd byte (b3) of MAC address

10.1.7 MAC[n].ADDRESS1 (n=0..1)

Address offset: 0x124 + (n × 0x8)

MAC address for VIFn

Least significant 2 bytes of MAC address b6:b5:b4:b3:b2:b1

Bit number				31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				B B B B B B B B A A A A A A A A
Reset 0xFFFFFFFF				**1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1**
ID	R/W	Field	Value ID	Value	Description
A	R	b2			2nd byte (b2) of MAC address
B	R	b1			1st byte (b1) of MAC address

10.1.8 CALIB.XO

Address offset: 0x130

XO adjustment

Adjusts capacitor bank, 0 : Lowest capacitance (Highest frequency), 127 : Highest capacitance (Lowest frequency)

Bit number				31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID																													A	A	A	A	A	A	A
Reset 0xFFFFFFFF				**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**
ID	R/W	Field	Value ID	Value								Description																							
A	RW	XO										XO adjustment																							

10.1.9 REGION_DEFAULTS

Address offset: 0x154

Customer region register usage indicator

Bit set to '0' indicate corresponding register is programmed

Bit number				31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID																																D	C	B	A
Reset 0xFFFFFFFF				**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**
ID	R/W	Field	Value ID	Value								Description																							
A	RW	QSPIKEY										QSPI.KEY state																							
B	RW	MAC0ADDRESS										MAC0.ADDRESS state																							
C	RW	MAC1ADDRESS										MAC1.ADDRESS state																							
D	RW	XO										CALIB.XO state																							

10.1.10 USERDATA[n] (n=0..25)

Address offset: 0x198 + (n × 0x4)

User data region

Bit number				31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID				A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A	A
Reset 0xFFFFFFFF				**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**	**1**
ID	R/W	Field	Value ID	Value								Description																							
A	RW	DATA										Data																							

11 Recommended operating conditions

The operating conditions are the physical parameters that the chip can operate within.

Symbol	Parameter	Min.	Nom.	Max.	Units
VBAT	VDD supply voltage	2.9	3.6	4.5	V
IOVDD	VDD supply voltage for IO pins	1.62	1.8	3.6	V
OTPVDD	VDD supply voltage for OTP memory (read mode)	1.62	1.8	1.98	V
OTPVDD	VDD supply voltage for OTP memory (write mode)	2.25	2.5	2.75	V
TA	Operating temperature	-40	25	85	°C

Table 10: Recommended operating conditions

12 Absolute maximum ratings

Maximum ratings are the extreme limits to which the chip can be exposed for a limited amount of time without permanently damaging it. Exposure to absolute maximum ratings for prolonged periods of time may affect the reliability of the device.

	Min.	Max.	Unit
Supply voltages			
VBAT	-0.3	4.5	V
IOVDD	-0.3	3.6	V
I/O pin voltage			
$V_{I/O}$, IOVDD ≤3.3 V	-0.3	IOVDD + 0.3	V
$V_{I/O}$, IOVDD >3.3 V	-0.3	3.6	V
BUCKEN	-0.3	VBAT + 0.3	V
Radio			
RF input level		-10	dBm
Environmental QFN package			
Storage temperature	-40	125	°C
Moisture Sensitivity Level (MSL)		2	
ESD Human Body Model (HBM)		750	V
ESD Charged Device Model (CDM)		1000	V

Table 11: Absolute maximum ratings

13 Electrical specification

This section provides a summary of nRF7000 electrical specifications.

VDD supply voltage is 3.6 V and operating temperature is 25°C unless otherwise noted.

Symbol	Parameter	Min.	Nom.	Max.	Units	Note
$f_{OP,2.4GHz}$	Operating frequencies 2.4 GHz	2401		2495	MHz	
$f_{OP,5GHz}$	Operating frequencies 5 GHz	5170		5330	MHz	U-NII-1/U-NII-2A sub-bands
		5490		5730		U-NII-2C sub-band
		5735		5895		U-NII-3/U-NII-4 sub-bands
$f_{MOD,MIN}$	Minimum modulation rate		1DSSS			2.4 GHz
			6 Mbps			5 GHz
$f_{MOD,MAX}$	Maximum modulation rate		6 Mbps			
f_{TOL}	Crystal frequency tolerance at 25°C[1]			20	ppm	
$f_{STA,TEMP}$	Crystal frequency stability over temperature and aging			13	ppm	
C_{L_XO}	XO load capacitance		8		pF	
ESR_{XO}	Equivalent Series Resistance			100	ohm	
$t_{SHUTDOWN→ACTIVE}$	Startup time from shutdown state		400		ms	Depends on patch size and interface speed
$t_{SLEEP→ACTIVE}$	Startup time from sleep state		6.7		ms	
t_{SCAN}	Scan time (2.4 and 5 GHz bands)		3.5		s	Using default scan parameters and World Zone regulatory rules (all channels and active scan where permitted)

Table 12: General characteristics

Symbol	Parameter	Min.	Nom.	Max.	Units	Note
$I_{TX,1DSSS,2.4GHz}$	Transmit current (2.4 GHz, 1DSSS, max output power)		252		mA	
$I_{TX,6Mbps,2.4GHz}$	Transmit current (2.4 GHz, 6 Mbps, max output power)		187		mA	
$I_{TX,6Mbps,5GHz}$	Transmit current (5 GHz, 6 Mbps, max output power)		260		mA	
$I_{RX,2.4GHz}$	Receive current listen (2.4 GHz)		60		mA	
$I_{RX,5GHz}$	Receive current listen (5 GHz)		56		mA	
I_{OFF}	Shutdown current		1.7		µA	
I_{SLEEP}	Sleep current (with RTC)		15		µA	
I_{SCAN}	Average current consumption during scan operation		60		mA	The exact current depends on the number of APs detected during scan. The value quoted aligns with ~100 APs.

Table 13: Current consumption

Symbol	Parameter	Min.	Nom.	Max.	Units	Note
$P_{TXMAX,2.4GHz,DSSS/}$	Maximum transmit power 2.4 GHz (DSSS)		20		dBm	
$P_{TXMAX,2.4GHz,6Mbps}$	Maximum transmit power 2.4 GHz (6 Mbps)		15		dBm	
$P_{TXMAX,5GHz,6Mbps}$	Maximum transmit power 5 GHz (6 Mbps)		13		dBm	

Table 14: Transmitter characteristics

[1] Tolerance before calibration. See Clock accuracy considerations on page 11 for more information.

Frequency band	-40C<TA<=-20C	-20C<TA<=0C	0C<TA<=60C	60C<TA<=85C
2.4GHz	0dB	0dB	0dB	-1dB
5GHz	-2dB	-1dB	0dB	-2dB

Table 15: Transmitter power variation over temperature

Frequency band	2.9V<VBAT<=3.1V	3.1V<VBAT<=3.4V	3.4V<VBAT<=4.5V
2.4GHz	-1dB	0dB	0dB
5GHz	-2dB	-1dB	0dB

Table 16: Transmitter power variation over supply voltage

Symbol	Parameter	Min.	Nom.	Max.	Units	Note
$P_{SENS,2.4GHz,1DSSS}$	Sensitivity 2.4GHz (1 Mbps DSSS)		-98.6		dBm	
$P_{SENS,2.4GHz,6MBPS}$	Sensitivity 2.4GHz (6 Mbps)		-91.6		dBm	
$P_{SENS,5GHz,6MBPS}$	Sensitivity 5.0GHz (6 Mbps)		-91.5		dBm	

Table 17: Receiver characteristics

14 Hardware and layout

This section describes nRF7000 hardware and layout specifications.

14.1 Pin assignments

The pin assignment figure and tables describe the pinouts for the device. There are also recommendations for how the *General-Purpose Input/Output (GPIO)* pins should be configured, in addition to any usage restrictions.

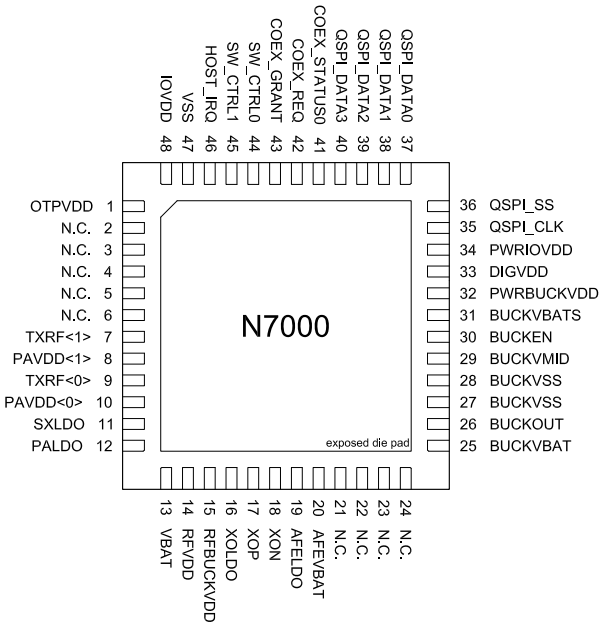


Figure 16: Pin assignments

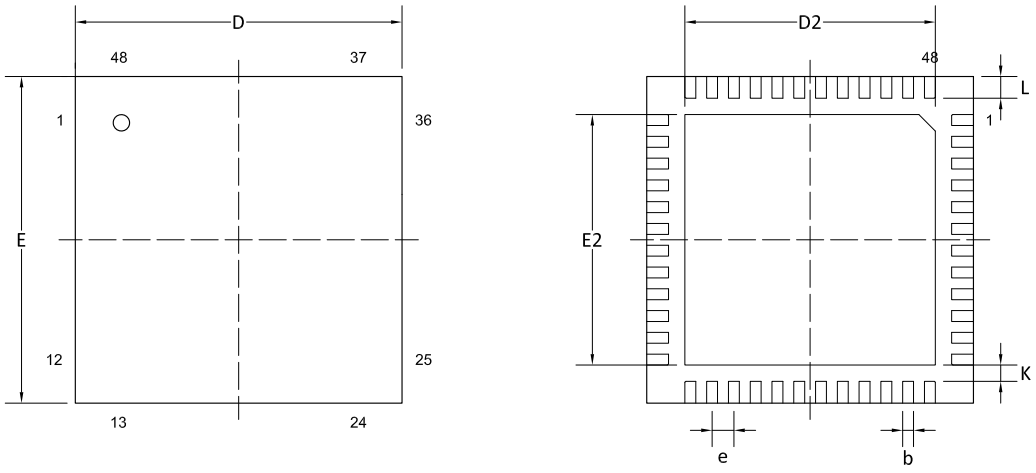
Pin	Name	Function	Description
1	OTPVDD	Power	
2	N.C.		Do not connect
3	N.C.		Do not connect
4	N.C.		Do not connect
5	N.C.		Do not connect
6	N.C.		Do not connect
7	TXRF<1>	RF	5 GHz
8	PAVDD<1>	Power	
9	TXRF<0>	RF	2.4 GHz
10	PAVDD<0>	Power	
11	SXLDO	Power	
12	PALDO	Power	
13	VBAT	Power	
14	RFVDD	Power	
15	RFBUCKVDD	Power	
16	XOLDO	Power	
17	XOP	Analog input	40 MHz crystal (or TCXO output if using an external TCXO)
18	XON	Analog input	40 MHz crystal (or N.C. if using an external TCXO)
19	AFELDO	Power	
20	AFEVBAT	Power	
21	N.C.		Do not connect
22	N.C.		Do not connect
23	N.C.		Do not connect
24	N.C.		Do not connect
25	BUCKVBAT	Power	
26	BUCKOUT	Power	DCDC output
27	BUCKVSS	Power	DCDC GND
28	BUCKVSS	Power	DCDC GND
29	BUCKVMID	Power	Voltage reference decoupling pin
30	BUCKEN	Digital I/O	PWR IP enable pin
31	BUCKVBATS	Power	
32	PWRBUCKVDD	Power	
33	DIGVDD	Power	
34	PWRIOVDD	Power	

Pin	Name	Function	Description
35	QSPI_CLK SPI_CLK	Digital I/O	QSPI Clock SPI Clock
36	QSPI_SS SPI_SS	Digital I/O	QSPI Slave select SPI Slave select
37	QSPI_DATA0 SPI_MOSI	Digital I/O	QSPI data SPI data
38	QSPI_DATA1 SPI_MISO	Digital I/O	QSPI data SPI data
39	QSPI_DATA2	Digital I/O	QSPI data
40	QSPI_DATA3	Digital I/O	QSPI data
41	COEX_STATUS0	Digital I/O	Coex interface
42	COEX_REQ	Digital I/O	Coex interface
43	COEX_GRANT	Digital I/O	Coex interface
44	SW_CTRL0	Digital I/O	External switch control
45	SW_CTRL1	Digital I/O	External switch control
46	HOST_IRQ	Digital I/O	Host processor interrupt request
47	VSS	Power	
48	IOVDD	Power	
49 (Die pad)	VSS	Power	Ground pad. Exposed die pad must be connected to ground (VSS) for proper device operation.

Table 18: Pin assignments

14.2 Mechanical specifications

Dimensions in millimeters for the QFN 6 x 6 mm package.



	A	A1	A2	b	D	E	D2	E2	e	K	L
Min.	0.8			0.15	5.9	5.9				0.2	0.35
Nom.	0.85	0.035	0.65	0.2	6	6	4.6	4.6	0.4		0.4
Max.	0.9	0.05		0.25	6.1	6.1					0.45

Table 19: Package dimensions in millimeters

14.3 Reference circuitry

To ensure good RF performance when designing *Printed Circuit Board (PCB)*s, it is highly recommended to use the PCB layouts and component values provided by Nordic Semiconductor.

14.3.1 Reference schematic

Circuit configuration, showing the schematic and Bill of Materials (BOM) table for nRF7000.

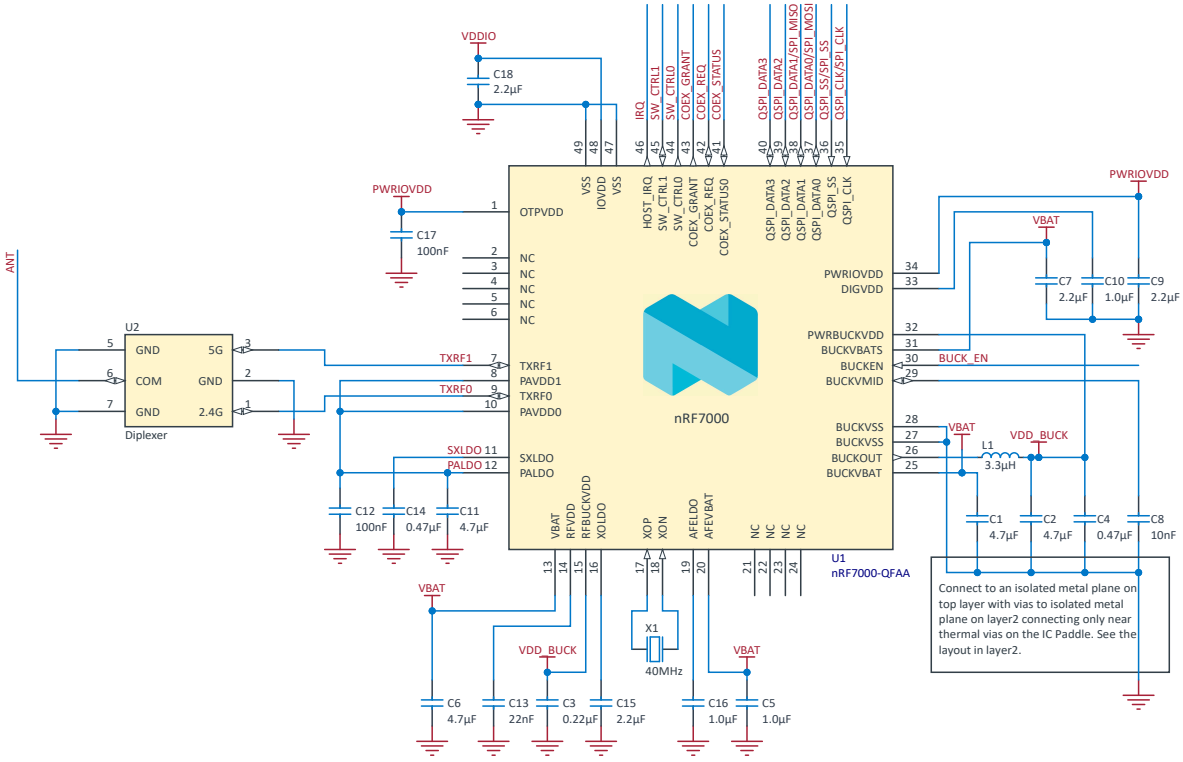


Figure 17: nRF7000 reference schematic

Designator	Value	Description	Note
U1	nRF7000	Dual Band Wi-Fi scan companion chip	
U2	2.4 / 5 GHz	WLAN Dual Band Diplexer	
X1	40 MHz	Crystal SMD 1612, 40 MHz, Cl=8 pF	ESR max 100 Ω
L1	3.3 µH	Inductor, 1 A, ±20%, 200 mΩ	
C1, C2, C6, C11	4.7 µF	Capacitor, Ceramic, 4.7 µF 25 V X6S 0603, ±10%	Place C1 close to BUCKVBAT pin Place C2 close to L1 Place C11 close to PALDO pin
C3	0.22 uF	Capacitor, Ceramic, 0.22 µF 10 V X5R 0201, ±10%	Place C3 close to RFBUCKVDD pin
C4, C14	0.47 uF	Capacitor, Ceramic, 0.47 µF 6.3 V X5R 0201, ±10%	Place C4 close to PWRBUCKVDD pin
C5	1.0 µF	Capacitor, Ceramic, 1.0 µF 35 V X5R 0402, ±10%	
C7, C18	2.2 µF	Capacitor, Ceramic, 2.2 µF 16 V X7S 0603, ±10%	Place C7 close to BUCKVBATS pin
C8	10 nF	Capacitor, Ceramic, 10 nF 16 V X7R 0201, ±10%	
C9	2.2 µF	Capacitor, Ceramic, 2.2 µF 25 V X5R 0402, ±10%	
C10	1.0 µF	Capacitor, Ceramic, 1.0 µF 16 V X6S 0402, ±10%	
C12	100 nF	Capacitor, Ceramic, 100 nF 16 V X7S 0201, ±10%	Place C12 close to PAVDD0 pin
C13	22 nF	Capacitor, Ceramic, 22 nF 10 V X5R 0201, ±10%	
C15	2.2 µF	Capacitor, Ceramic, 2.2 µF 10 V X5R 0201, ±10%	
C16	1.0 µF	Capacitor, Ceramic, 1.0 µF 10 V X7S 0402, ±10%	
C17	100 nF	Capacitor, Ceramic, 100 nF 16 V X7S 0201, ±10%	

Table 20: BOM for nRF7000

14.3.2 Supply sequencing requirements

The various supplies and BUCKEN need to be sequenced in order with delay requirements.

The power up sequence and requirements are:

- Supply VBAT/BUCKVBAT/BUCKVBATS/AFEVBAT
- Wait ≥ 6 ms
- Assert BUCKEN
- Wait ≥ 1 ms
- Supply IOVDD

PWRIOVDD is an internally generated supply, used for supplying OTPVDD through an external connection. It cannot be used for anything else. This supply is automatically controlled in the device.

The power-down sequence and requirements are:

- De-assert BUCKEN and power down IOVDD
- Power down VBAT

There are no specific timing delay requirements as long as the sequence is correct.

14.3.3 Supply system

nRF7000 can be powered up/down from a host dynamically. This dynamic control uses the BUCKEN pin and an external switch to control the IOVDD supply. Both the BUCKEN pin and the external switch control are driven from a *GPIO* on the host, controlled by the Wi-Fi driver.

The following figure shows the recommended connection between nRF7000 and the host *MCU* (nRF9160).

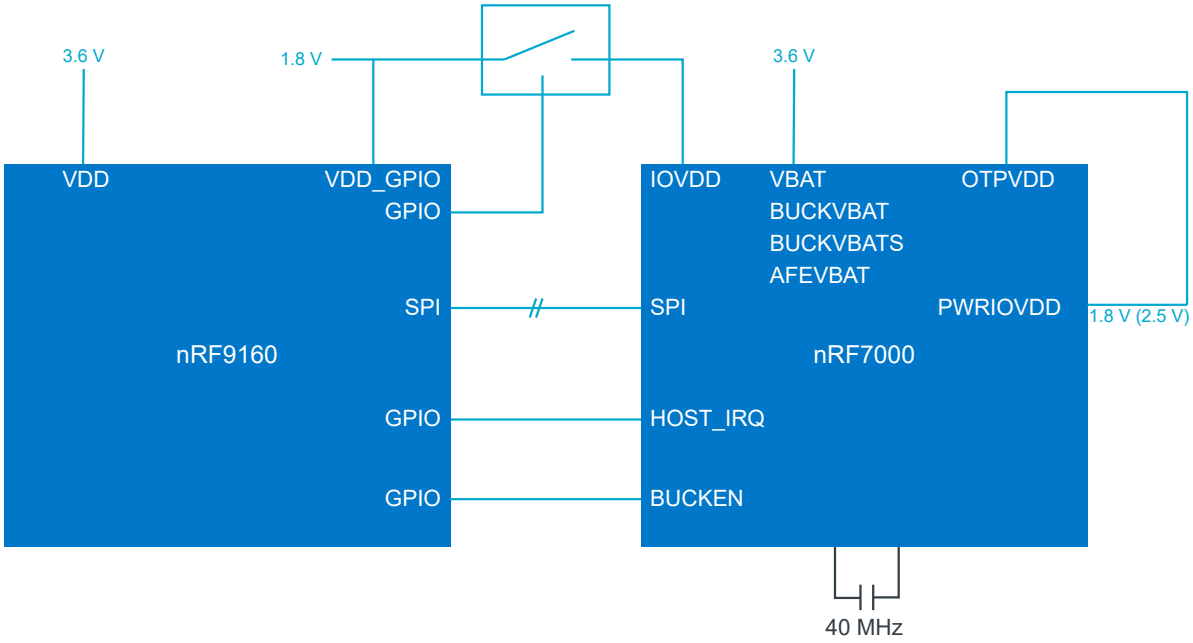


Figure 18: Supply system

14.3.4 QSPI/SPI connections

The nRF7000 can be connected to a host with either a *QSPI* or a *SPI*. QSPI is normally the preferred option for the nRF5340 host, while SPI is used with the nRF9160 host.

The following figure shows the connection using QSPI between nRF7000 and nRF5340.

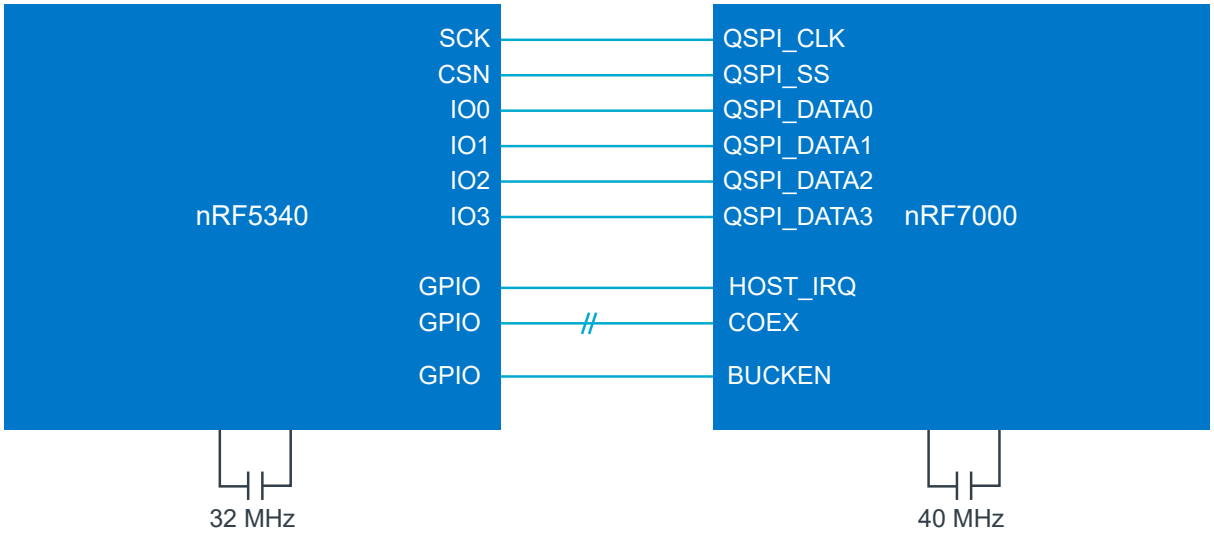


Figure 19: QSPI connection

The following figure shows the connections using SPI between nRF7000 and nRF9160.

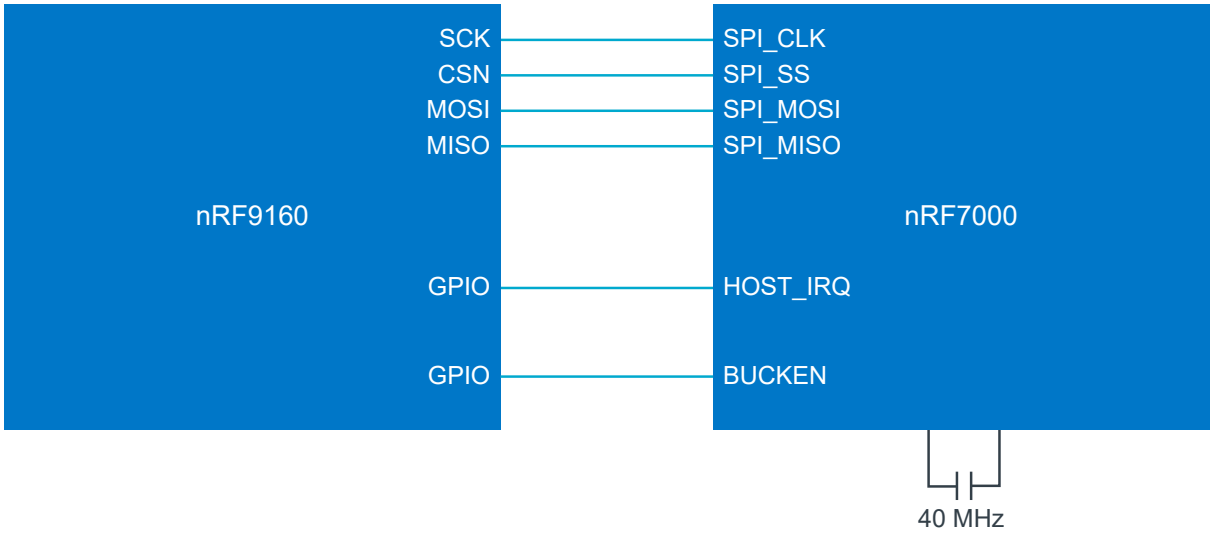


Figure 20: SPI connection

14.3.5 TCXO connection

It is possible to use an external TCXO instead of a crystal.

This option does not require production line trimming, but it will draw more current and hence significantly degrade sleep performance. The TCXO should be disabled when in Shutdown mode to reduce current consumption. It is not possible to dynamically control the TCXO when transitioning between Sleep and Active states. The TCXO should have a typical clipped sine wave output of 0.4 V peak (maximum 0.6 V peak) and be connected through a series capacitor (typically 10 nF).

14.3.6 PCB layout example

The *PCB* layout in this section is a reference layout for the QFN package.

It is highly recommended to use the layout example as presented with the following boundary clarifications:

- Keep the antenna connection short.
- Connect VBAT supply to component **C6** in the bottom layer.

- Connect IOVDD supply to component **C18** in the bottom layer.

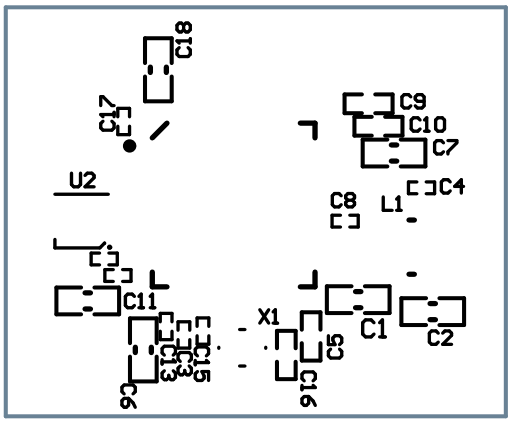


Figure 21: Top silk layer

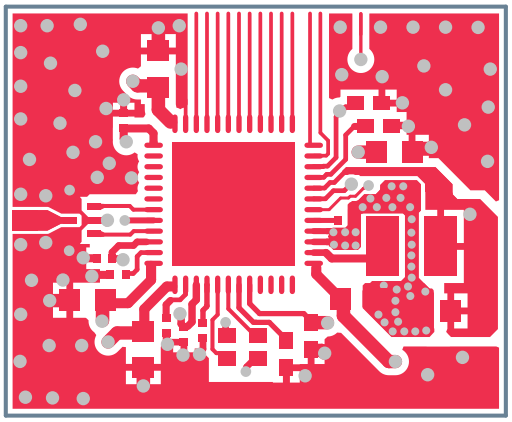


Figure 22: Top layer

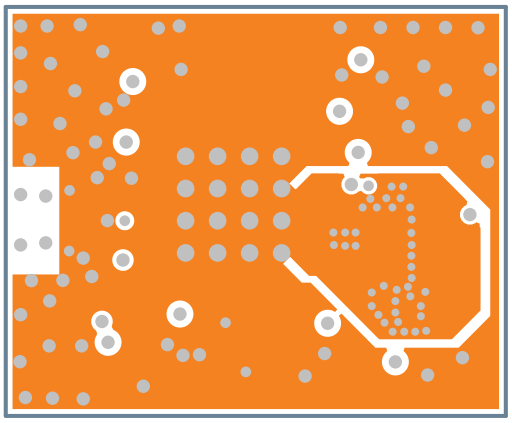


Figure 23: Mid layer 1

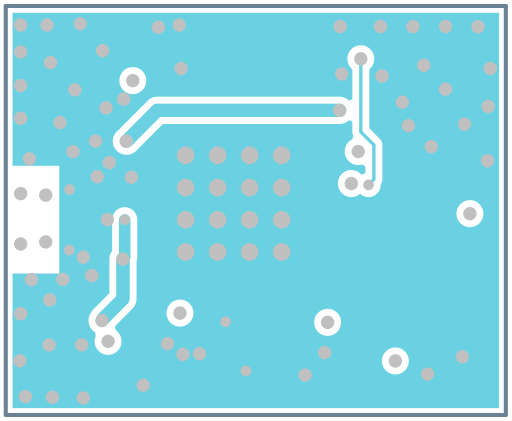


Figure 24: Mid layer 2

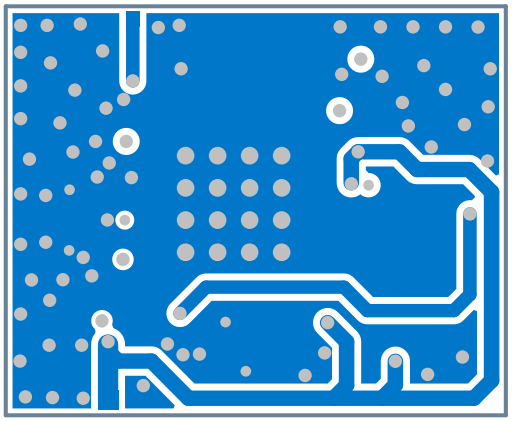


Figure 25: Bottom layer

15 Ordering information

This chapter contains information on IC marking, ordering codes, and container sizes.

15.1 Device marking

The nRF7000 package is marked as shown in the following figure.

N	7	0	0	0	
<P	P>	<V	V>	<H>	<P>
<Y	Y>	<W	W>	<L	L>

Figure 26: IC marking

15.2 Box labels

The following figures define the box labels used for the nRF7000.

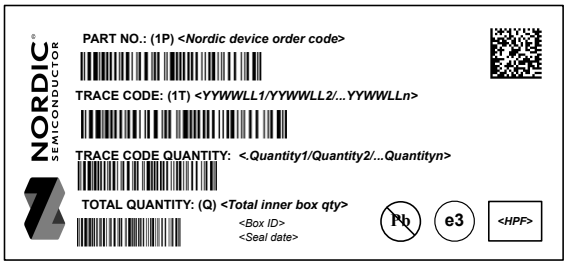


Figure 27: Inner box label

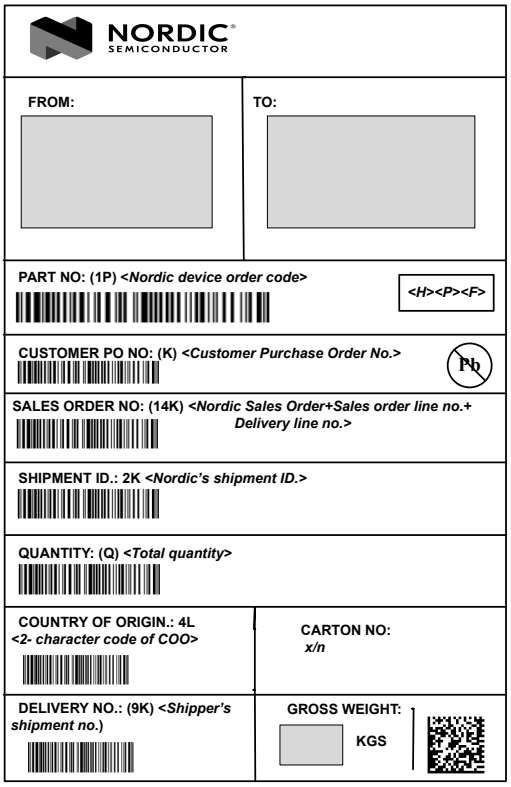


Figure 28: Outer box label

15.3 Order code

The following tables define the nRF7000 order codes and definitions.

n	R	F	7	0	0	0	-	<P	P>	<V	V>	-	<C	C>

Figure 29: Order code

Abbreviation	Definition and implemented codes
N70/nRF70	nRF70 series product
00	Part code
<PP>	Package variant code
<VV>	Function variant code
<H><P><F>	Build code H - Hardware version code P - Production configuration code (production site, etc.) F - Firmware version code (only visible on shipping container label)
<YY><WW><LL>	Tracking code YY - Year code WW - Assembly week number LL - Wafer lot code
<CC>	Container code

Table 21: Abbreviations

15.4 Code ranges and values

The following tables define the nRF7000 code ranges and values.

<PP>	Package	Size (mm)	Pin/Ball count	Pitch (mm)
QF	QFN	6 x 6	48	0.4

Table 22: Package variant codes

<VV>	Variant
AA	Base functionality

Table 23: Function variant codes

<H>	Description
[A . . Z]	Hardware version/revision identifier (incremental)

Table 24: Hardware version codes

<P>	Description
[0 . . 9]	Production device identifier (incremental)
[A . . Z]	Engineering device identifier (incremental)

Table 25: Production configuration codes

<F>	Description
[A . . N, P . . Z]	Version of preprogrammed firmware
[0]	Delivered without preprogrammed firmware

Table 26: Production version codes

<YY>	Description
[16 . . 99]	Production year: 2016 to 2099

Table 27: Year codes

<WW>	Description
[1 . . 52]	Week of production

Table 28: Week codes

<LL>	Description
[AA . . ZZ]	Wafer production lot identifier

Table 29: Lot codes

<CC>	Description
R7	7" Reel
R	13" Reel

Table 30: Container codes

15.5 Product options

This section defines nRF7000 order codes and minimum ordering quantities (MOQ).

Order code	MOQ
nRF7000-QFAA-R7	1000
nRF7000-QFAA-R	3000

Table 31: nRF7000 order codes

Glossary

Analog-to-Digital Converter (ADC)

A system that converts an analog signal, such as a sound picked up by a microphone or light entering a digital camera, into a digital signal.

Application Programming Interface (API)

A language and message format used by an application program to communicate with an operating system, application, or other service.

Basic Service Set Identifier (BSSID)

A unique address that identifies the access point/router that creates the wireless network.

Carrier Wave (CW)

A single-frequency electromagnetic wave that can be modulated in amplitude, frequency, or phase to convey information.

Digital-to-Analog Converter (DAC)

A system that converts a digital signal into an analog signal.

Delivery Traffic Indication Message (DTIM)

A Traffic Indication Message (TIM) that informs clients about the presence of buffered multicast/ broadcast data on the access point.

Factory Information Configuration Registers (FICR)

Pre-programmed registers that contain chip-specific information and configuration. FICRs cannot be erased by users.

General-Purpose Input/Output (GPIO)

A digital signal pin that can be used as input, output, or both. It is uncommitted and can be controlled by the user at runtime.

Internet of Things (IoT)

Physical objects that are embedded with sensors, processing ability, software, and other technologies that connect and exchange data with other devices and systems of the Internet or other communications networks.

Medium Access Control (MAC)

The layer that controls the hardware responsible for interaction with the wired, optical, or wireless transmission medium.

Microcontroller Unit (MCU)

A small computer on a single metal-oxide-semiconductor integrated circuit chip.

Memory Protection Unit (MPU)

A computer hardware unit that provides memory protection and is usually implemented as part of the CPU.

One Time Programmable (OTP) memory

A type of non-volatile memory that permits data to be written to memory only once.

Packet Traffic Arbitration (PTA)

A collaborative coexistence mechanism for collocated wireless protocols.

Physical (PHY)

The first and lowest layer of computer networking. This layer is closely associated with the physical connection between devices.

Power Management Unit (PMU)

A microcontroller that controls power functions of digital platforms.

Printed Circuit Board (PCB)

A board that connects electronic components.

Pulse-Frequency Modulation (PFM)

A modulation method for representing an analog signal using only two levels (1 and 0).

Pulse-Width Modulation (PWM)

A method of reducing the average power delivered by an electrical signal, by effectively dividing it into discrete parts.

Quad Serial Peripheral Interface (QSPI)

A *SPI* controller that allows the use of multiple data lines.

RC oscillator

A linear oscillator circuit that uses a combination of resistors and capacitors for its frequency selective element.

Real-time Clock (RTC)

An electronic device that keeps accurate track of time.

Serial Peripheral Interface (SPI)

Synchronous serial communication interface specification used for short-distance communication.

Service Set Identifier (SSID)

A unique identifier assigned to a wireless local area network.

System on Chip (SoC)

A microchip that integrates all the necessary electronic circuits and components of a device or other electronic systems on a single integrated circuit.

Vector Signal Analyzer (VSA)

A signal analyzer capable of analyzing digitally-modulated radio signals that may use any of a large number of digital modulation formats.

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Version 2, June 1991

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```

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Nordic Semiconductor ASA's products are not designed for use in life-critical medical equipment, support appliances, devices, or systems where malfunction of Nordic Semiconductor ASA's products can reasonably be expected to result in personal injury. Customer may not use any Nordic Semiconductor ASA's products in life-critical medical equipment unless adequate design and operating safeguards by customer's authorized officers have been made. Customer agrees that prior to using or distributing any life-critical medical equipment that include Nordic Semiconductor ASA's products, customer will thoroughly test such systems and the functionality of such products as used in such systems.

Customer will fully indemnify Nordic Semiconductor ASA and its representatives against any damages, costs, losses, and/or liabilities arising out of customer's non-compliance with this section.

RoHS and REACH statement

Refer to www.nordicsemi.com for complete hazardous substance reports, material composition reports, and latest version of Nordic's RoHS and REACH statements.

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